On Market Microstructure Noise and Realized Volatility

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The Hansen-Lunde (HL) research program is generally first-rate, displaying a rare blend of theoretical prowess and applied sense. The present paper is no exception. In a major theoretical advance, HL allow for correlation between microstructure (MS) noise and latent price (I prefer “latent price” to terms such as “efficient price” or “true price,” which carry lots of excess baggage). In a parallel major substantive advance, they provide a pioneering empirical investigation of the nature of the correlation between MS noise and latent price, documenting a negative correlation at high frequencies.

The significance of the Hansen-Lunde (HL) contribution, and my admiration of it, hinges on the contributions noted above and is indeed most genuine. Nevertheless, much of what follows is rather critical of the extant literature, including certain key elements of the HL approach. My intention is that the criticism be constructive, promoting and hastening additional progress.

1. On the Dynamics of Latent Price

HL work in the framework:

\[ p(t) = p^*(t) + \nu(t) \]  \hspace{1cm} (1)

\[ dp^*(t) = \mu dt + \sigma(t)dW(t) \]  \hspace{1cm} (2)

where \( p(t) \) is observed (log) price, \( p^*(t) \) is the latent (log) price, \( \nu(t) \) is MS noise, \( \mu \) is a fixed expected return (actually HL go even farther and restrict \( \mu=0 \)), and \( dW \) is an increment of standard Brownian motion. Without additional assumptions equation (1) is tautological, simply defining MS noise as \( \nu(t) = p(t) - p^*(t) \). Hence everything hinges on the assumed specifications of \( p^*(t) \) and \( \nu(t) \) – neither of

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which is observable! – and assumptions regarding their interaction.

Prior to HL, the literature effectively focused on specifications with latent price assumed uncorrelated with the MS noise,

\[ \text{corr}(v(t), dW(t)) = 0. \]  

(3)

HL progress by allowing instead,

\[ \text{corr}(v(t), dW(t)) = \rho. \]  

(4)

Importantly, their allowance for \( \text{corr}(v(t), dW(t)) \neq 0 \) accords with both MS theory (more on this later) and with empirical fact (as HL emphasize).

However, the HL specification (1), (2), (4) remains quite limited relative to one allowing for time-varying expected returns and jumps, as in:

\[ dp^\ast(t) = \mu(t) dt + \sigma(t)dW(t) + \kappa(t)dg(t), \]  

(5)

where \( \mu(t) \) is the time-varying expected return, \( \kappa(t) = p(t) - p(t^-) \) is jump size, and \( g(t) \) is a counting process with possibly time-varying intensity \( \lambda(t) \) such that \( P[dg(t) = 1] = \lambda(t)dt \).

First consider the possibility of time-varying expected returns. Note that \( p^\ast(t) \) is a real-world price, not a risk-neutral price, so there is no reason for \( p^\ast(t) \) to follow a martingale. Hence allowance for time-varying expected returns is important in principle. In practice one might argue that, at least in high-frequency environments (e.g., hourly returns used to construct daily realized volatility (RV)), time-variation in expected returns is likely to be negligible and can therefore be safely ignored. Fair enough, but at least three caveats are in order. First, and obviously, interest sometimes centers not on high-frequencies, but rather on lower frequencies such as annual RV constructed from underlying monthly returns, particularly in historical asset market studies covering long calendar spans. Second, there is evidence of non-martingale behavior not only at long horizons, but also at short horizons (e.g., Lo and MacKinlay, 2001). Hence even if interest does center on high-frequency returns, it is not obvious that time-varying expected returns can be safely ignored. Finally, Elliott’s (1998) well-known work establishes that cointegration methods are not robust even to slight deviations from I(1) behavior in the underlying variables. In the present case (and moving to discrete time to match the standard cointegration framework), the required I(1) behavior is for \( p^\ast \) and hence \( p_T \), which is apparently not guaranteed when time-variation in expected returns is allowed.

This concern is particularly relevant to the present paper, a large part of which is devoted to cointegration analysis.

Now consider jumps. Jumps are an important feature of empirical reality, and frameworks that ignore them do so at their own peril. This insight arises repeatedly in many studies presenting estimates of
parametric jump-diffusion models for asset returns, and it is reinforced and amplified by recent nonparametric volatility analyses (see, e.g., Andersen, Bollerslev and Diebold, 2005, and the references therein) and examinations of the financial market reaction to macroeconomic news (e.g., Andersen, Bollerslev, Diebold and Vega, 2003). Indeed, given that incorporation of MS noise and jumps are widely acknowledged as two of the most pressing items on the RV research agenda, it is unfortunate that although the RV-jumps literature acknowledges MS noise (e.g., Barndorff-Nielsen and Shephard, 2004, 2005a, 2005b; Andersen, Bollerslev and Diebold, 2005), the latest significant advance of the RV-MS literature (namely HL) does not acknowledge jumps. I look forward to additional HL progress rectifying that situation.

2. On the Inadequacy of Linear/Gaussian Methods

For simplicity of exposition, assume that both the observed and latent prices evolve at transaction times, and that transaction times are equally spaced.

The HL framework corresponds to a linear discrete-time state space system:

$$P_t = P_t^* + \epsilon_t$$

(6)

$$P_t^* = p_{t-1}^* + \sigma_t \mu_t$$

(7)

$$\begin{pmatrix} \epsilon_t \\ \mu_t \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} \sigma_t^2 \\ \sigma_{\mu t} \\ \sigma_{\mu u} \\ 1 \end{pmatrix} \right)$$

(8)

The system may or may not be conditionally Gaussian, depending on the dynamics of $\sigma_t$. If, for example, $\sigma_t$ has GARCH structure such as

$$\sigma_t^2 = \omega + \alpha u_{t-1}^2 + \beta \sigma_{t-1}^2,$$  

(9)

then the system is conditionally Gaussian, but if $\sigma_t$ has stochastic volatility structure such as

$$\sigma_t^2 = \omega + \beta \sigma_{t-1}^2 + \eta_t$$

(10)

$$\eta_t \sim \mathcal{N} (0, \sigma_\eta^2),$$

then the system is not conditionally Gaussian. Of course the realized volatility framework makes only minimal assumptions on $\sigma_t$ and is compatible with both GARCH and stochastic volatility, among many
Quite apart from such details, however, the intrinsic mechanics of the leading MS noise candidates (and the ones explicitly used by HL to motivate their approach), namely bid/ask bounce and discrete price quotes, induce fundamental violations of the linear/Gaussian state space framework that appear to have been ignored in the RV-MS literature thus far. To see this, dispense for the moment with volatility dynamics, because including them only complicates matters without changing the basic point.

Consider in particular a MS model in the tradition of Hasbrouck (1999a,b), incorporating both bid/ask bounce and discrete pricing:

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\begin{align*}
\pi_t &= \begin{cases} 
\text{floor}(q_t^b, \text{ticksize}) & \text{if } \pi_t = 0 \\
\text{ceiling}(q_t^a, \text{ticksize}) & \text{if } \pi_t = 1 
\end{cases} \\
q_t^b &= p_t^* - c_t \\
q_t^a &= p_t^* + c_t \\
p_t^* &= p_{t-1}^* + u_t \\
\pi_t &\sim \text{Bernoulli}(0.5) \\
c_t &\sim N(\mu_c, \sigma_c^2) \\
u_t &\sim N(0, \sigma_u^2) 
\end{align*}
$$

where $q_t^b$ is the bid price, $q_t^a$ is the ask price, $2c_t$ is the bid/ask spread that represents the positive stochastic cost of dealer quote exposure, $\pi_t$ is a bid/ask indicator variable, floor($\cdot$, d) rounds its argument down to the closest multiple of ticksize and ceiling($\cdot$, d) rounds up, and $u_t$, $c_t$ and $\pi_t$ are contemporaneously and serially independent.

The MS model (11)-(16) also constitutes a state space system, relating the observed $p_t$ to the latent
but the bid/ask bounce and rounding render it intrinsically non-Gaussian. Against this background, I worry about the adequacy of the linear/Gaussian tools on which HL rely: HAC estimation based on sample autocorrelations, Gaussian cointegrated VARs, etc.

In closing this section, let me also note that the state space framework raises the possibility of direct filtering or smoothing of MS noise from observed returns, before proceeding to compute RV. This is of independent interest, as one might want to use MS-corrected returns for a variety of purposes beyond construction of MS-corrected RV. For the reasons discussed above, however, the optimal filter will generally be non-linear, and hence the Kalman filter will be suboptimal. Diebold and Vega (2002) explore optimal nonlinear MS noise filtering, and Owens and Steigerwald (2005) independently explore Kalman MS noise filtering. An interesting and open issue concerns the goodness of approximation of the Kalman filter to the fully optimal filter.

Alternatively, if interest centers exclusively on volatility, one can first construct realized volatility and then filter to reduce MS noise (as well as estimation error due to incomplete convergence of RV to underlying integrated volatility). This is the approach implicitly taken by HL, although they do not attempt to construct an optimal nonlinear filter tailored to the structure of the MS noise. It is also the approach taken explicitly in Andersen, Bollerslev, Diebold and Wu (2005, 2006), who analyze explicit state-space systems but use only a Kalman filter.

3. On the Theoretical and Empirical Correlation Between MS Noise and Latent Price

In a pioneering substantive contribution, HL discover a negative relationship between latent returns and MS noise at high frequencies. Does the negative correlation match the predictions of MS theory? HL claim rather casually that the answer is yes, arguing that “the correlation between noise and efficient price arises naturally in some models of market microstructure effects, including (a generalized version of) the bid-ask model by Roll (1984) ... and models where agents have asymmetric information, such as those by Glosten and Milgrom (1985) and Easley and O’Hara (1987, 1992).”

In fact the situation is more nuanced, with some MS considerations suggesting a positive correlation, and others suggesting negative, so that on net the correlation could be empirically positive, negative, or even zero. The issues are well-illustrated by the generalized Roll model emphasized by HL (see Roll, 1984, and Hasbrouck, 1999a, 1999b, 2004), which can produce either positive or negative correlation, as follows.

Let us first generate a positive correlation. Focusing for simplicity only on bid/ask bounce (that is,
ignoring the discreteness of price quotes), rewrite the system (11)-(16) in condensed notation as

\[ p_t = p_t^* + c q_t, \]

\[ p_t^* = p_{t-1}^* + u_t, \]

where \( q_t \) indicates direction of trade (1 for a buy, and -1 for a sell). Also refine (13) by decomposing the latent price increment as

\[ u_t = \lambda q_t + \omega_t, \]

where \( \lambda \) is the reaction of latent price to a trade and hence captures some aspects of private information, and \( \omega_t \) denotes public information. Simple calculations then reveal that

\[ \text{cov}(\Delta p_t^*; \Delta (p_t - p_t^*)) = E(\lambda q_t + \omega_t) c(q_t - q_{t-1}) = c\lambda E(q_t^2) = c\lambda > 0, \]

if \( q_t \) is independent of \( \omega_t \) and independent over time, as is commonly assumed.

Now let us generate a potentially negative correlation by allowing for sluggish adjustment of transactions prices, which could arise for a variety of reasons, such as learning. We replace (17) with

\[ p_t = p_{t-1}^* + c q_t, \]

yielding

\[ \text{cov}(\Delta p_t^*; \Delta (p_t - p_t^*)) = (c - \lambda)\lambda - E(\omega_t^2), \]

which can be negative if \( c \) is small relative to \( \lambda \) and the variance of \( \omega_t \) is large. It is interesting to note that MS models in the tradition of Glosten and Milgrom (1985), Kyle (1985), and Easley and O’Hara (1987, 1992) all assume similar adjustment lags and hence predict negative correlation.

The upshot: it is trivial to write down a microstructure model with either a negative or a positive contemporaneous correlation between latent returns and MS noise. The basic insight is that certain factors promote overreaction of observed price to movements in latent price and hence a positive correlation, while other factors promote underreaction of observed price to movements in latent price and hence a negative correlation. Different models (or different variants of the same model) emphasize different factors. Empirically, moreover, several such factors may be operative simultaneously, and whether they aggregate to something negative or positive is an empirical matter. Hence the negative estimates obtained by HL do not necessarily “support” or “refute” any particular MS model.

In any event, a rich vein remains to be mined. The discussion in HL (and thus far in this comment) focuses only on the contemporaneous correlation between latent price and MS noise. The contemporaneous correlation, however, is just the tip of the iceberg. The entire cross-correlation structure associated with the
transmission of latent price movements into eventual observed price movements is of great interest, and little is known about it, whether theoretically or empirically. Diebold and Strasser (2005) provide an initial exploration.
References


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